

How to receive codes from a wireless remote on your Raspberry Pi.

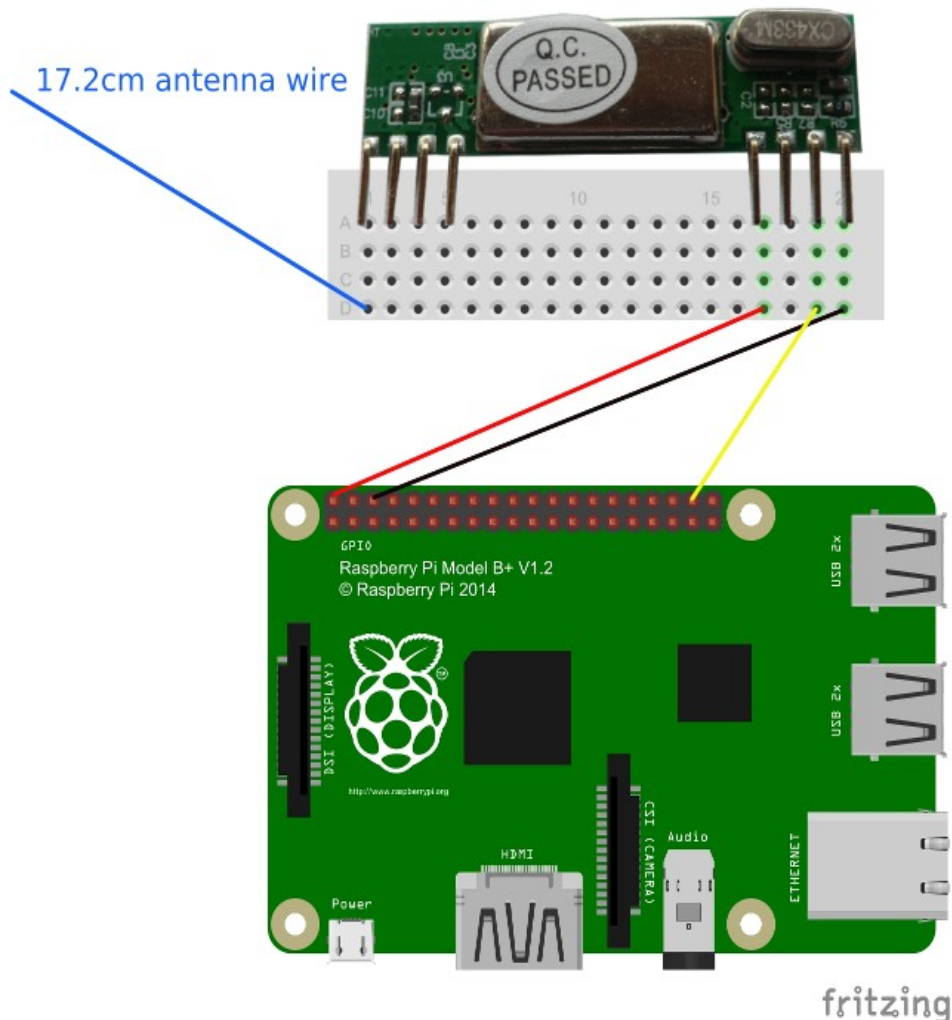
This guide will show you how to receive signals from most remote control gadgets that use the 433MHz (Europe) and 315MHz (North America) bands. The software will only receive AM signals that are transmitted using Manchester / OOK type encoding scheme.

(If you're interested in transmitting & receiving signals at 315MHz, 434MHz, 868MHz or 915MHz using FSK, GFSK, 2-FSK modulation, possibly over long distances, see our other PDF for the TI CC1101 radio modules & Raspberry Pi – www.securipi.co.uk/cc1101.pdf)

You need a suitable 433MHz or 315MHz receiver board connected to your Pi. The really cheap boards can only receive signals from up to 3 metres away. A decent crystal-controlled shielded super-heterodyne board only costs a few extra £s, and will pick up signals through walls from a 20 metre distance. <http://www.ebay.co.uk/itm/161662463558>

The receiver boards usually have three pins labelled 5V, GND and Data. The PiGPIO library and Python script looks for a connection on GPIO 20 by default, which is fine if you own a Pi A+, B+ or Pi2. If you have an older model B Pi, with less GPIO pins, you should edit the _433.py Python script so it looks for a connection on RX27 (GPIO27) instead of RX20 (GPIO20).

Here's how the 433Mhz receiver connects to GPIO20 on the A+, B+ or Pi 3




```
pi@raspberrypi ~/pigpio/PIGPIO $ python _433.py
code=5592332 bits=24 (gap=10270 t0=335 t1=997)
code=5592332 bits=24 (gap=10270 t0=334 t1=998)
code=5592332 bits=24 (gap=10270 t0=335 t1=997)
code=5592332 bits=24 (gap=10269 t0=334 t1=998)
code=5592332 bits=24 (gap=10270 t0=334 t1=998)
code=5592332 bits=24 (gap=10271 t0=334 t1=998)
code=5592512 bits=24 (gap=10270 t0=335 t1=999)
code=5592512 bits=24 (gap=10275 t0=335 t1=999)
code=5592512 bits=24 (gap=10275 t0=334 t1=999)
code=5592512 bits=24 (gap=10270 t0=335 t1=998)
code=5592512 bits=24 (gap=10270 t0=334 t1=999)
code=5592512 bits=24 (gap=10270 t0=334 t1=998)
code=5592323 bits=24 (gap=10275 t0=335 t1=999)
code=5592323 bits=24 (gap=10275 t0=335 t1=999)
code=5592323 bits=24 (gap=10275 t0=335 t1=999)
code=5592323 bits=24 (gap=10275 t0=336 t1=998)
code=5592368 bits=24 (gap=10270 t0=335 t1=999)
code=5592368 bits=24 (gap=10275 t0=335 t1=999)
code=5592368 bits=24 (gap=10275 t0=335 t1=999)
code=5592368 bits=24 (gap=10275 t0=335 t1=999)
```

A variety of information is produced. The gap=, t0= and t1= values are useful if you want to re-transmit the codes you've received. The only information needed for receiving is the code= part.

The _433.py program runs for 60 seconds and then quits. Most remotes transmit the same code several times in a row, as a protection against wireless interference.

The codes that start 5592 are all produced by a simple 4 button 433MHZ remote control. I've written them down, along with the button they correspond to, and will use them in a shell script that interacts with a patched version of _433.py that I've called r433.py. I only changed a couple of lines:

```
for i in range(args-1):
    print("sending {}".format(sys.argv[i+1]))
    tx.send(int(sys.argv[i+1]))
    time.sleep(1)

    tx.cancel() # Cancel the transmitter.

    time.sleep(0.5)

    rx.cancel() # Cancel the receiver.

    pi.stop() # Disconnect from local Pi.
```

you can pull the r433.py and 433test.sh commands down from our server with

```
wget www.securipi.co.uk/r433.py
```

and

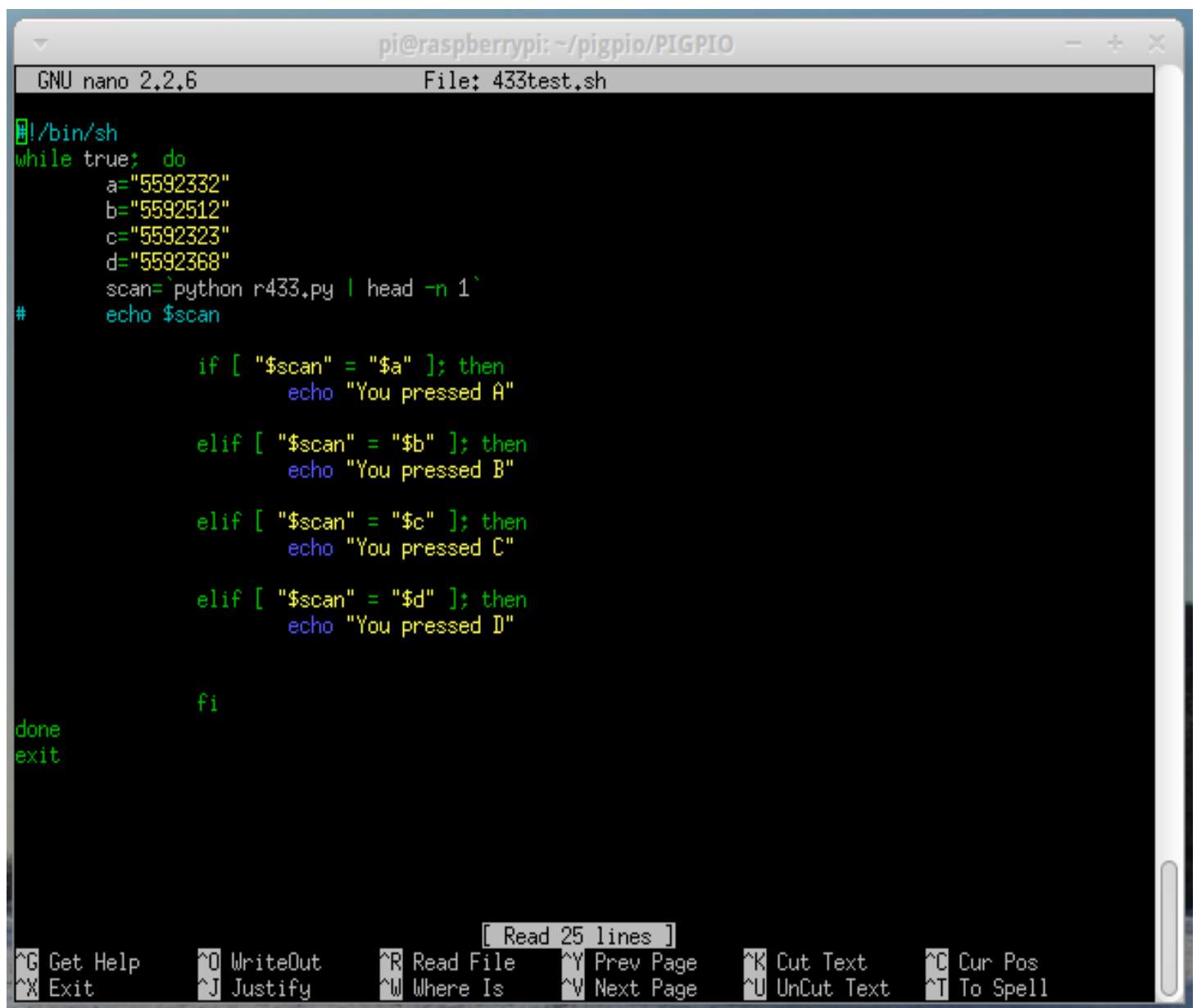
```
wget www.securipi.co.uk/433test.txt  
mv 433test.txt 433test.sh
```

make the shell script executable with

```
chmod a+x 433test.sh
```

run the script with

```
./433test.sh
```



```
pi@raspberrypi: ~/pigpio/PIGPIO  
GNU nano 2.2.6 File: 433test.sh  
#!/bin/sh  
while true; do  
    a="5592332"  
    b="5592512"  
    c="5592323"  
    d="5592368"  
    scan=`python r433.py | head -n 1`  
    # echo $scan  
  
    if [ "$scan" = "$a" ]; then  
        echo "You pressed A"  
    elif [ "$scan" = "$b" ]; then  
        echo "You pressed B"  
    elif [ "$scan" = "$c" ]; then  
        echo "You pressed C"  
    elif [ "$scan" = "$d" ]; then  
        echo "You pressed D"  
    fi  
  
done  
exit
```

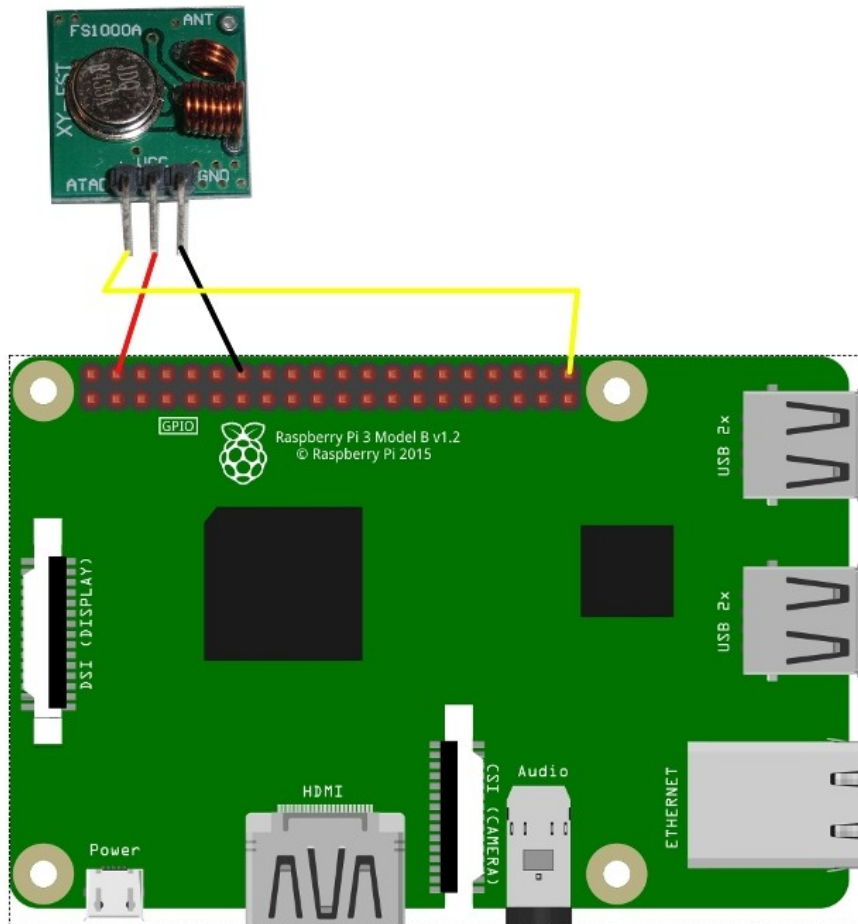
[Read 25 lines]

^G Get Help	^O WriteOut	^R Read File	^Y Prev Page	^K Cut Text	^C Cur Pos
^X Exit	^J Justify	^W Where Is	^V Next Page	^U UnCut Text	^T To Spell

Transmitting signals.

When we ran the `_433.py` receiver software we saw the code, bits, gap and t0 and t1 values for our remote control. If you wrote those down it's possible to use a 433Mhz transmitter module, to replay those codes using the Raspberry Pi.

The transmitter module has 3 pins: 5 volt, ground GND and Data. The data pin attaches to GPIO 21, below the receiver data pin 20. 5 volt and ground also attach to spare pins on the Pi.



fritzing

We've written a small python script that displays a menu of buttons on the desktop, and currently emulates the 4 button remote control transmitter keyfob seen here:

<https://www.amazon.co.uk/dp/B01DOJ9XEW>



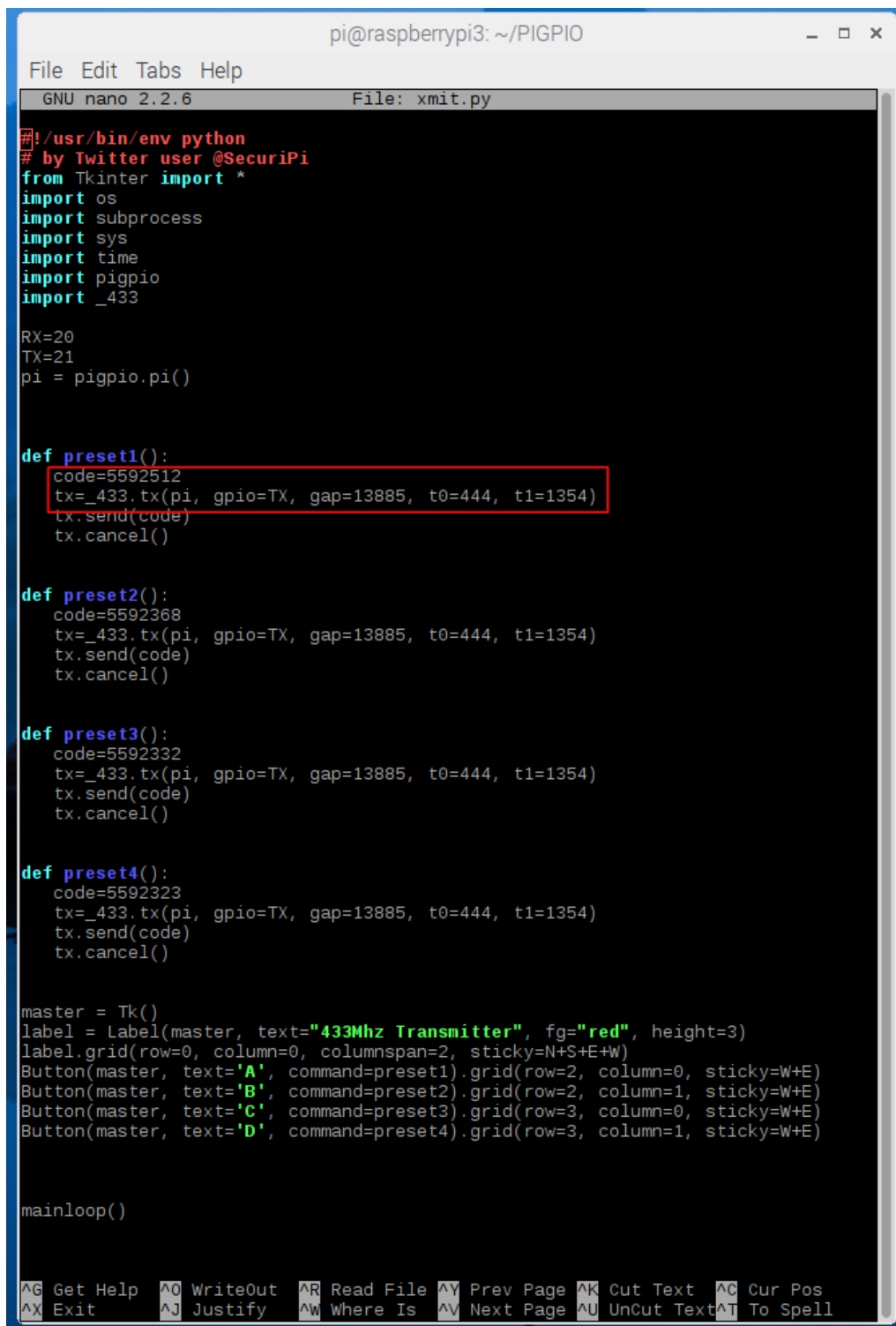
Pull the code down from our server with:

```
wget http://www.securipi.co.uk/xmit.py
```

and run it on your Pi's desktop by opening a terminal window and typing

```
python xmit.py
```

You can modify the code to contain your own gadget's codes, gap, T0 and T1 settings.



The image shows a terminal window titled 'pi@raspberrypi3: ~/PIGPIO'. The window contains the code for a Python script named 'xmit.py' being edited in nano 2.2.6. The code is as follows:

```
#!/usr/bin/env python
# by Twitter user @SecuriPi
from Tkinter import *
import os
import subprocess
import sys
import time
import pigpio
import _433

RX=20
TX=21
pi = pigpio.pi()

def preset1():
    code=5592512
    tx=_433.tx(pi, gpio=TX, gap=13885, t0=444, t1=1354)
    tx.send(code)
    tx.cancel()

def preset2():
    code=5592368
    tx=_433.tx(pi, gpio=TX, gap=13885, t0=444, t1=1354)
    tx.send(code)
    tx.cancel()

def preset3():
    code=5592332
    tx=_433.tx(pi, gpio=TX, gap=13885, t0=444, t1=1354)
    tx.send(code)
    tx.cancel()

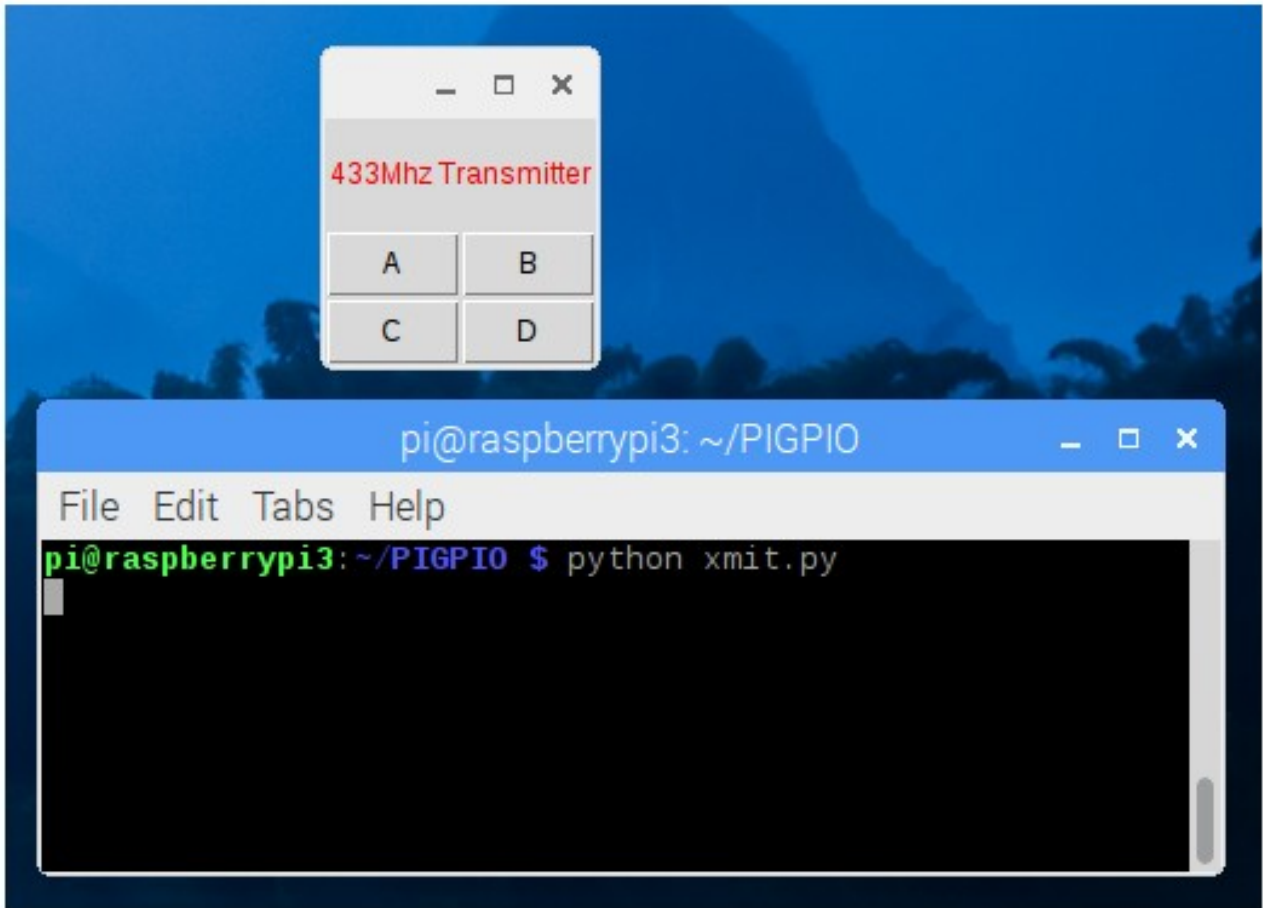
def preset4():
    code=5592323
    tx=_433.tx(pi, gpio=TX, gap=13885, t0=444, t1=1354)
    tx.send(code)
    tx.cancel()

master = Tk()
label = Label(master, text="433Mhz Transmitter", fg="red", height=3)
label.grid(row=0, column=0, columnspan=2, sticky=N+S+E+W)
Button(master, text='A', command=preset1).grid(row=2, column=0, sticky=W+E)
Button(master, text='B', command=preset2).grid(row=2, column=1, sticky=W+E)
Button(master, text='C', command=preset3).grid(row=3, column=0, sticky=W+E)
Button(master, text='D', command=preset4).grid(row=3, column=1, sticky=W+E)

mainloop()

^G Get Help ^O WriteOut ^R Read File ^Y Prev Page ^K Cut Text ^C Cur Pos
^X Exit ^J Justify ^W Where Is ^V Next Page ^U UnCut Text ^T To Spell
```

This is the python script xmit.py running on the Pi's desktop. You can use it to send button codes to the receiver module that came with the 433Mhz keyfob.



Remote control mains sockets.

In this chapter we'll look at using the Raspberry Pi to automatically control a 3 pack of remote control mains sockets, that we've bought from eBay.



We've made a new receiver script called testrx1.py which prints out detected codes from 433.92Mhz wireless gadgets and also stores them in a comma-delimited file called 433log.txt.

```
import sys
import time
import pigpio
import _433
from time import sleep
from signal import pause

RX=20
pi = pigpio.pi()
def rx_callback(code, bits, gap, t0, t1):
    print("code={} bits={} (gap={} t0={} t1={})".
          format(code, bits, gap, t0, t1))
    file = open("433log.txt", "a")
    file.write(str(code)+',')
    file.write(str(bits)+',')
    file.write(str(gap)+',')
    file.write(str(t0)+',')
    file.write(str(t1)+'\n')
    file.close()

_433.rx(pi, gpio=RX, callback=rx_callback)
pause()
```

Assuming you've got already got the PIGPIO daemon running (sudo pigpiod), run the python

receiver script with:

```
python testrx1.py
```

When we press the on and off buttons for sockets 1 and 2 we get this output.

```
pi@raspberrypi3: ~/PIGPIO
pi@raspberrypi3:~/PIGPIO $ python testrx1.py
code=9775839 bits=24 (gap=9580 t0=300 t1=884)
code=9775839 bits=24 (gap=9585 t0=306 t1=879)
code=9775839 bits=24 (gap=9615 t0=304 t1=880)
code=9775839 bits=24 (gap=9590 t0=304 t1=881)
code=9775838 bits=24 (gap=9580 t0=300 t1=884)
code=9775838 bits=24 (gap=9585 t0=300 t1=885)
code=9775838 bits=24 (gap=9605 t0=307 t1=878)
code=9775838 bits=24 (gap=9625 t0=301 t1=883)
code=9775838 bits=24 (gap=9595 t0=300 t1=884)
code=9775837 bits=24 (gap=9585 t0=300 t1=884)
code=9775837 bits=24 (gap=9585 t0=302 t1=883)
code=9775837 bits=24 (gap=9610 t0=300 t1=884)
code=9775837 bits=24 (gap=9585 t0=300 t1=884)
code=9775836 bits=24 (gap=9580 t0=300 t1=884)
code=9775836 bits=24 (gap=9581 t0=299 t1=885)
code=9775836 bits=24 (gap=9590 t0=302 t1=883)
code=9775836 bits=24 (gap=9625 t0=299 t1=885)
code=9775836 bits=24 (gap=9600 t0=299 t1=885)
█
```

You can inspect the 433log.txt file with

```
cat 433log.txt
```

or

```
nano 433log.txt
```

```
pi@raspberrypi3: ~/PIGPIO
pi@raspberrypi3:~/PIGPIO $ cat 433log.txt
9775839,24,9580,300,884
9775839,24,9585,306,879
9775839,24,9615,304,880
9775839,24,9590,304,881
9775838,24,9580,300,884
9775838,24,9585,300,885
9775838,24,9605,307,878
9775838,24,9625,301,883
9775838,24,9595,300,884
9775837,24,9585,300,884
9775837,24,9585,302,883
9775837,24,9610,300,884
9775837,24,9585,300,884
9775836,24,9580,300,884
9775836,24,9581,299,885
9775836,24,9590,302,883
9775836,24,9625,299,885
9775836,24,9600,299,885
pi@raspberrypi3:~/PIGPIO $ █
```

On the previous two screens we could see that the last two digits of the Code would change each time we pressed a button, so:

```
9775839 = socket 1 on
9775838 = socket 1 off
9775837 = socket 2 on
9775836 = socket 2 off
```

The bits were always set to 24. The Gap, T0 and T1 values changed around a little but are basically all near enough that you could choose any set and they'll work with all the Code values.

This next script allows us to turn the sockets on and off at preset times using a Python script on the Raspberry Pi.

```
nano timer.py
```

```
import sys
import time
import pigpio
import _433
import datetime
import os
import subprocess

TX=21
pi = pigpio.pi()

def on1():
    code=9775839
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def off1():
    code=9775838
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def on2():
    code=9775837
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def off2():
    code=9775836
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

while True:
```

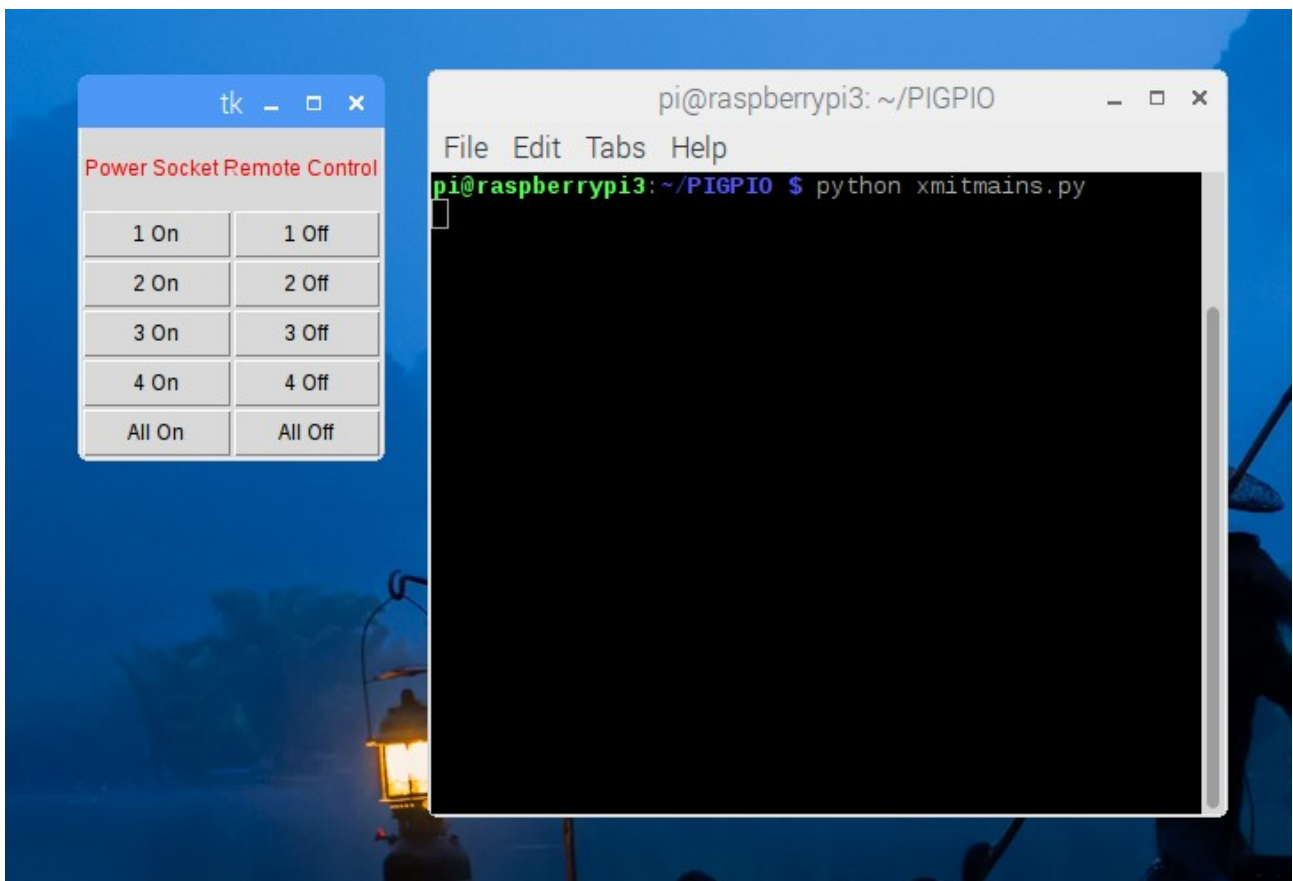
```
now = datetime.datetime.now()
if now.hour == 19 and now.minute == 47 and now.second == 00:
    print 'Turning socket 1 on'
    on1()
    time.sleep(2)
elif now.hour == 19 and now.minute == 49 and now.second == 00:
    print 'Turning socket 1 off'
    off1()
    time.sleep(2)
if now.hour == 19 and now.minute == 54 and now.second == 00:
    print 'Turning socket 2 on'
    on2()
    time.sleep(2)
elif now.hour == 19 and now.minute == 54 and now.second == 20:
    print 'Turning socket 2 off'
    off2()
    time.sleep(2)
```

run it with :

```
python timer.py
```

The script turns socket 1 on at 19:47:00 and off again two minutes later. It also turns socket 2 on at 19:54:00 and off again 20 seconds later.

We also made a graphical desktop widget that can control the mains adapters, called xmitmains.py, which looks like this:



```
#!/usr/bin/env python
# by Twitter user @SecuriPi
from Tkinter import *
import os
import subprocess
import sys
import time
import pigpio
import _433

RX=20
TX=21
pi = pigpio.pi()

def on1():
    code=9775839
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def off1():
    code=9775838
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def on2():
    code=9775837
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def off2():
    code=9775836
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def on3():
    code=9775835
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def off3():
    code=9775834
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def on4():
    code=9775831
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def off4():
    code=9775830
```

```
tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
tx.send(code)
tx.cancel()

def allon():
    code=9775826
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

def alloff():
    code=9775825
    tx=_433.tx(pi, gpio=TX, gap=9580, t0=299, t1=885)
    tx.send(code)
    tx.cancel()

master = Tk()
label = Label(master, text="Power Socket Remote Control", fg="red",
height=3)
label.grid(row=0, column=0, columnspan=2, sticky=N+S+E+W)
Button(master, text='1 On', command=on1).grid(row=2, column=0, sticky=W+E)
Button(master, text='1 Off', command=off1).grid(row=2, column=1, sticky=W+E)
Button(master, text='2 On', command=on2).grid(row=3, column=0, sticky=W+E)
Button(master, text='2 Off', command=off2).grid(row=3, column=1, sticky=W+E)
Button(master, text='3 On', command=on3).grid(row=4, column=0, sticky=W+E)
Button(master, text='3 Off', command=off3).grid(row=4, column=1, sticky=W+E)
Button(master, text='4 On', command=on4).grid(row=5, column=0, sticky=W+E)
Button(master, text='4 Off', command=off4).grid(row=5, column=1, sticky=W+E)
Button(master, text='All On', command=allon).grid(row=6, column=0,
sticky=W+E)
Button(master, text='All Off', command=alloff).grid(row=6, column=1,
sticky=W+E)

mainloop()
```

Replaying a captured code

It's possible to have the Pi listen out for wireless codes and then offer to replay the code, without having to type in all the parameters separately. I've also added the option of replaying a different code, but with the same Gap, T0 and T1 values. There's also an option to transmit codes in a range, with a step value – so I can turn my mains sockets all off or on, 1 at a time. The script is called `replay2.py`

```
#!/usr/bin/env python
# by Twitter user @SecuriPi
import sys
import time
import pigpio
import _433
from time import sleep
from signal import pause

TX=21
RX=20
pi = pigpio.pi()

def rx_callback(code, bits, gap, t0, t1):
    if bits == 24:
        print("code={} bits={} (gap={} t0={} t1={})".
              format(code, bits, gap, t0, t1))
        # Write info to 433log.txt file
        file = open("433log.txt","a")
        file.write(str(code)+'\n')
        file.write(str(bits)+'\n')
        file.write(str(gap)+'\n')
        file.write(str(t0)+'\n')
        file.write(str(t1)+'\n')
        file.close()
        option = raw_input('replay received code y/n OR c to change the
code OR input r for Range: ')
        if option == 'y':
            tx=_433.tx(pi, gpio=TX, gap=gap, t0=t0, t1=t1)
            tx.send(code)
            tx.cancel()
            pi.stop
        if option == 'c':
            code = input('enter new code to send: ')
            tx=_433.tx(pi, gpio=TX, gap=gap, t0=t0, t1=t1)
            tx.send(code)
            tx.cancel()
        if option == 'r':
            code = input('enter lowest code: ')
            endCode = input('enter highest code: ')
            stepCode = input('enter step value: ')
            while code <= endCode:
                tx=_433.tx(pi, gpio=TX, gap=gap, t0=t0, t1=t1)
                tx.send(code)
                tx.cancel()
                print('sending code '+str(code))
```

```

        code += stepCode
        time.sleep(1)
    else:
        print "exiting back to receiver mode"

_433.rx(pi, gpio=RX, callback=rx_callback)
pause()

```

You have to be careful when replaying codes to keep the receiver and transmitter modules more than 6 inches apart, otherwise the Gap, T0 and T1 values will inexplicably grow each time you replay the codes. (You can always look in the 433log.txt file for the original values of Gap, T0 and T1).

```

pi@raspberrypi3: ~/PIGPIO $ python replay2.py
code=9775839 bits=24 (gap=9580 t0=299 t1=885)
replay received code y/n OR c to change the code OR input r for Range: c
enter new code to send: 9775838
exiting back to receiver mode
code=9775839 bits=24 (gap=9615 t0=303 t1=881)
replay received code y/n OR c to change the code OR input r for Range:
exiting back to receiver mode
code=9775839 bits=24 (gap=9595 t0=301 t1=883)
replay received code y/n OR c to change the code OR input r for Range:
exiting back to receiver mode

code=9775838 bits=24 (gap=9580 t0=301 t1=883)
replay received code y/n OR c to change the code OR input r for Range: e
code=9775838 bits=24 (gap=9595 t0=300 t1=883)
replay received code y/n OR c to change the code OR input r for Range:
exiting back to receiver mode
code=9775838 bits=24 (gap=9630 t0=302 t1=881)
replay received code y/n OR c to change the code OR input r for Range:
exiting back to receiver mode

```

The following equipment is tested & works fine with our scripts:
 Lloytron MIP range of wireless Doorbell pushes, PIR movement and Magnetic Door Sensors.
 Status 3 pack mains remote controlled sockets
 433Mhz version of 4 button pocket keyfob transmitter/receiver for Pi and Arduino projects.

All the scripts in this PDF also work with the 315MHz equivalents used in North America.

Notes & Useful Sales Links.

Make sure you remember to run the PIGPIO daemon each time you start the Pi (sudo pigpiod), or add it to your /etc/rc.local file, so it launches each time you power up the Pi.

Buy 433MHz if you're in the UK or Europe. Buy 315MHz if you're in North America.

You can buy the really good 433MHz receiver board from our eBay shop here:

<http://www.ebay.co.uk/itm/433Mhz-Shielded-Low-Noise-Wireless-Receiver-Board-for-Raspberry-Pi-Arduino-/161662463558?roken=cUgayN>

We also sell a 433Mhz transmitter/receiver pair here:

http://cgi.ebay.co.uk/ws/eBayISAPI.dll?ViewItem&item=161594608707#ht_500wt_1180

(the transmitter is great, the receiver isn't anywhere near as good as the shielded low-noise version)

You can buy the 4 button keyfob 433Mhz version here:

http://cgi.ebay.co.uk/ws/eBayISAPI.dll?ViewItem&item=131767939665#ht_609wt_1165

The 315MHz version of the shielded receiver board for North America is here in our eBay shop:

<http://www.ebay.co.uk/itm/315Mhz-Shielded-Low-Noise-Wireless-Receiver-Board-for-Raspberry-Pi-Arduino-/162023269288>

The 315Mhz version of the 4 button keyfob for North America is here:

<http://www.ebay.co.uk/itm/4-channel-315MHz-wireless-remote-control-for-Raspberry-Pi-Arduino-UK-Stock-/161651775043>

Also, our **433MHz Internet Doorbell kits for Raspberry Pi** (£20) come with the 433MHz Shielded receiver board and a wireless 433MHz door push that emails photos of callers to your phone:

Black <https://www.amazon.co.uk/dp/B00UL9QBJ4>

White <https://www.amazon.co.uk/dp/B00UL3FRGS>

No bell push <https://www.amazon.co.uk/dp/B00T4DUYMS>

We also do some **Home Security kits for Raspberry Pi:**

SecuriPi PIR sensor alarm kit, photos of intruders to your phone £11.99

<https://www.amazon.co.uk/dp/B00GOPJJWU>

Magnetic sensor window/door alarm kit for Raspberry Pi £12.99

<https://www.amazon.co.uk/dp/B00DBDT6TY>

48 Infra Red LED lighting kit for Raspberry Pi PiNoIR camera £15.99

<https://www.amazon.co.uk/dp/B015OA6VAI>

And a Home Security kit with PIR and Magnetic sensor that links supplied Arduino to your PC or Mac for £18.99 : <https://www.amazon.co.uk/dp/B00P9UTF0W>

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Manchester encoding info : https://en.wikipedia.org/wiki/Manchester_encoding

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